On the Theory of Mathematical Forms

Ken Kubota

2015

```
:= A5311 \%0
                             \supset (\exists_1 t [\lambda y.(py)]) (p(\iota p))_o
# wff
            5461 :
                                                                     := A5311
##
##
       Q.E.D.
##
\%0
                       \supset (\exists_1 t [\lambda y.(p y)]) (p (\iota p))
#
#
                       \supset_{ooo}(\exists_{1o(o\setminus3)\tau}t_{\tau}[\lambda y_t.(p_{ot}y_t)_o])(p_{ot}(\iota_{t(ot)}p_{ot}))
                                                                                   := A5311
            Results for File A5313.r0.txt
5.1.44
##
       Proof A5313: (C_t_x_y_T = x) \land (C_t_x_y_F = y)
##
##
##
##
       Source: [Andrews 2002 (ISBN 1-4020-0763-9), p. 235 f.]
##
       Copyright (c) 2015 Owl of Minerva Press GmbH. All rights reserved.
##
##
       Written by Ken Kubota (<mail@kenkubota.de>).
##
       This file is part of the work "On the Theory of Mathematical Forms".
##
##
       For more information visit: <a href="http://dx.doi.org/10.4444/100.10">http://dx.doi.org/10.4444/100.10</a>
##
       "C[t]xyp can be read 'if p then x, else y'." [Andrews 2002, p. 235]
##
##
<< basics.r0.txt
<< A5205.r0.txt
<< A5231.r0.txt
<< K8000.r0.txt
<< K8001.r0.txt
<< K8010.r0.txt
:= CHOOS \dots
\dots [\lambda t_{\tau}.[\lambda x_t.[\lambda y_t.[\lambda p_o.(\iota_{t(ot)}[\lambda q_t.(\vee_{ooo}(\wedge_{ooo}p_o(=_{ott}x_tq_t))(\wedge_{ooo}(\sim_{oo}p_o)(=_{ott}y_tq_t)))_o])_t]_{(tot)}]_{(tot)}]
                                 [\lambda t.[\lambda x.[\lambda y.[\lambda p.(\iota [\lambda q.(\lor (\land p (= x q)) (\land (\sim p) (= y q)))])]]]_{\land 4o \land 3 \land 2\tau}
# wff
             2080 :
CHOOS
##
## Proof
```

```
##
## .1
= t_{\tau} CHOOS_{\langle 4o \rangle 3 \langle 2\tau} t_{\tau} x_t y_t T_o
                              = (CHOOS t x y T) (CHOOS t x y T)
= (CHOOS\ t)\ [\lambda x.[\lambda y.[\lambda p.(\iota\ [\lambda q.(\lor (\land p\ (=x\ q))\ (\land (\sim p)\ (=y\ q)))])]]]
\S s \% 1 24 \% 0
#
                              = (CHOOS\,t\,x\,y\,T)\,([\lambda x.[\lambda y.[\lambda p.(\iota\,[\lambda q.(\vee\,(\wedge\,p\,(=\,x\,q))\,(\wedge\,(\sim\,p)\,(=\,y\,q)))])]]|\,x\,y\,T)
 \{ \langle \lambda x_t [\lambda y_t [\lambda p_o.(\iota_{t(ot)}[\lambda q_t.(\vee_{ooo}(\wedge_{ooo}p_o(=_{ott}x_tq_t))(\wedge_{ooo}(\sim_{oo}p_o)(=_{ott}y_tq_t)))_o] \}_{(tot)}] x_t \} 
                              = ([\lambda x.[\lambda y.[\lambda p.(\iota [\lambda q.(\vee (\wedge p (= x q)) (\wedge (\sim p) (= y q)))])]]]x) \dots
\ldots [\lambda y.[\lambda p.(\iota [\lambda q.(\vee (\wedge p (= x q)) (\wedge (\sim p) (= y q)))])]]
\S s \% 1 12 \% 0
                              = (CHOOS\,t\,x\,y\,T)\,([\lambda y.[\lambda p.(\iota\,[\lambda q.(\vee\,(\wedge\,p\,(=\,x\,q))\,(\wedge\,(\sim\,p)\,(=\,y\,q)))])]]\,y\,T)
#
 \{ \langle \lambda y_t [\lambda p_o.(\iota_{t(ot)}[\lambda q_t.(\vee_{ooo}(\wedge_{ooo}p_o(=_{ott}x_tq_t))(\wedge_{ooo}(\sim_{oo}p_o)(=_{ott}y_tq_t)))_o]\}_{t(to)} \} y_t 
                              = ([\lambda y.[\lambda p.(\iota [\lambda q.(\vee (\wedge p (= x q)) (\wedge (\sim p) (= y q)))])]]y) \dots
\dots [\lambda p.(\iota [\lambda q.(\vee (\wedge p (=x q)) (\wedge (\sim p) (=y q)))])]
\$s \%1 6 \%0
                              = \left( CHOOS\,t\,x\,y\,T\right) \left( \left[ \lambda p. (\iota\left[ \lambda q. (\vee\left( \wedge\,p\left( = x\,q\right) \right) \left( \wedge\left( \sim\,p\right) \left( = y\,q\right) \right) \right) \right] \right) \right] T )
#
\{ \langle \lambda p_o.(\iota_{t(ot)}[\lambda q_t.(\vee_{ooo}(\wedge_{ooo}p_o(=_{ott}x_tq_t))(\wedge_{ooo}(\sim_{oo}p_o)(=_{ott}y_tq_t)))_o] \rangle_t | T_o \}
                              = ([\lambda p.(\iota [\lambda q.(\vee (\wedge p (= x q)) (\wedge (\sim p) (= y q)))])]T) \dots
\ldots (\iota [\lambda q.(\vee (\wedge T (= x q)) (\wedge (\sim T) (= y q)))])
\S s \% 1 3 \% 0
                              = (CHOOS t x y T) (\iota [\lambda q.(\lor (\land T (= x q)) (\land (\sim T) (= y q)))])
#
:= LTMP5313 \%0
# wff
                  2115
                                                = (CHOOS t x y T) (\iota [\lambda q.(\vee (\wedge T (= x q)) (\wedge (\sim T) (= y q)))])_{\alpha}
\$LTMP5313
## .2
\S = _{o} /15
                              = (\lor (\land T (= xq)) (\land (\sim T) (= yq))) (\lor (\land T (= xq)) (\land (\sim T) (= yq)))
#
\% A5231a
                              = (\sim T) F
#
                                                     := A5231a
                              =_{ooo}(\sim_{oo}T_o)F_o
                                                             := A5231a
\S s \% 1 29 \% 0
                              = (\vee (\wedge T (= x q)) (\wedge (\sim T) (= y q))) (\vee (\wedge T (= x q)) (\wedge F (= y q)))
#
:= \$TMP5313 \%0
                                           = (\lor (\land T (= x q)) (\land (\sim T) (= y q))) (\lor (\land T (= x q)) (\land F (= y q)))_{q}
# wff
                 2120
$TMP5313
\%K8001b
#
                              = (\wedge F x) F
                                                         := K8001b
                              =_{ooo}(\wedge_{ooo}F_ox_o)F_o
                                                                   := K8001b
## use Proof Template A5221 (Sub): B \rightarrow B [x/A]
:= \$B5221 \%0
```

```
= (\wedge F x) F_{o, \dots}
                                              := \$B5221 \ K8001b
# wff
           1805 :
:= T5221 o
# wff
           2:
                               := T5221
                       O_{\mathcal{T}}
:= \$X5221 \ x_o
# wff
           16 :
                                := \$X5221
                        x_o
:= $A5221 \%1/15
          2069 :
                                       := $A5221
# wff
                          = y q_o
<< A5221.r0t.txt
:= \$B5221
:= T5221
:= $X5221
:= $A5221
\%0
                    = (\wedge F (= y q)) F
#
                    =_{ooo}(\wedge_{ooo}F_o(=_{ott}y_tq_t))F_o
\%$TMP5313
                             = (\vee (\wedge T (= x q)) (\wedge (\sim T) (= y q))) (\vee (\wedge T (= x q)) (\wedge F (= y q)))
$TMP5313
                    =_{ooo}(\vee_{ooo}(\wedge_{ooo}T_o(=_{ott}x_tq_t))(\wedge_{ooo}(\sim_{oo}T_o)(=_{ott}y_tq_t)))\dots
\dots (\vee_{ooo}(\wedge_{ooo}T_o(=_{ott}x_tq_t))(\wedge_{ooo}F_o(=_{ott}y_tq_t))) \qquad := \$TMP5313
:= \$TMP5313
\S s \% 0 7 \% 1
                    = (\vee (\wedge T (= x q)) (\wedge (\sim T) (= y q))) (\vee (\wedge T (= x q)) F)
#
:= TMP5313 \%0
                          = (\lor (\land T (= x q)) (\land (\sim T) (= y q))) (\lor (\land T (= x q)) F)_{q} := \$TMP5313
           2155 :
# wff
\%K8000b
                    = (\wedge T x) x
                                    := K8000b
#
                    =_{ooo}(\wedge_{ooo}T_ox_o)x_o := K8000b
## use Proof Template A5221 (Sub): B \rightarrow B [x/A]
:= \$B5221 \%0
                         = (\wedge T x) x_{o...}
                                             := \$B5221 \ K8000b
# wff
           594 :
:= T5221 o
# wff
         2:
                               := T5221
:= \$X5221 \ x_o
          16 :
                                := \$X5221
# wff
                        x_o
:= $A5221 \% 1/43
# wff
          2064 :
                                       := $A5221
                          = x q_o
<< A5221.r0t.txt
:= \$B5221
:= T5221
:= $X5221
:= $A5221
\%0
                    = (\wedge T (= x q)) (= x q)
#
                    =_{ooo}(\wedge_{ooo}T_o(=_{ott}x_tq_t))(=_{ott}x_tq_t)
```

```
\%$TMP5313
                        = (\vee (\wedge T (= x q)) (\wedge (\sim T) (= y q))) (\vee (\wedge T (= x q)) F) \qquad := \$TMP5313
#
#
                        =_{ooo}(\vee_{ooo}(\wedge_{ooo}T_o(=_{ott}x_tq_t))(\wedge_{ooo}(\sim_{oo}T_o)(=_{ott}y_tq_t)))(\vee_{ooo}(\wedge_{ooo}T_o(=_{ott}x_tq_t))F_o)
:= \$TMP5313
:= \$TMP5313
\S s \% 0 13 \% 1
                       = (\vee (\wedge T (= x q)) (\wedge (\sim T) (= y q))) (\vee (= x q) F)
:= \$TMP5313 \%0
                              = (\lor (\land T (= x q)) (\land (\sim T) (= y q))) (\lor (= x q) F)_{o} := \$TMP5313
# wff
             2191 :
\%K8010a
                       = (\vee x F) x := K8010a
#
                       =_{ooo}(\vee_{ooo}x_oF_o)x_o := K8010a
## use Proof Template A5221 (Sub): B \rightarrow B [x/A]
:= \$B5221 \%0
                              = (\lor x F) x_o := \$B5221 \ K8010a
# wff
             2028 :
:= T5221 o
# wff
          2 :
                          o_{\tau} := T5221
:= \$X5221 \ x_o
# wff
                           x_o := \$X5221
           16 :
:= $A5221 \%1/13
# wff
            2064 :
                              = x q_{o, \dots}
                                              := \$A5221
<< A5221.r0t.txt
:= \$B5221
:= T5221
:= \$X5221
:= $A5221
\%0
                       = (\lor (= x q) F) (= x q)
#
                       =_{ooo}(\vee_{ooo}(=_{ott}x_tq_t)F_o)(=_{ott}x_tq_t)
\%$TMP5313
                       = (\vee \left( \wedge T \left( = x \, q \right) \right) \left( \wedge \left( \sim T \right) \left( = y \, q \right) \right) \right) \left( \vee \left( = x \, q \right) F \right) \qquad := \quad \$TMP5313
#
                            =_{ooo}(\vee_{ooo}(\wedge_{ooo}T_o(=_{ott}x_tq_t))(\wedge_{ooo}(\sim_{oo}T_o)(=_{ott}y_tq_t)))(\vee_{ooo}(=_{ott}x_tq_t)F_o)
#
TMP5313
:= \$TMP5313
\S s \% 0 3 \% 1
                       = (\vee (\wedge T (= x q)) (\wedge (\sim T) (= y q))) (= x q)
#
## .3
%$LTMP5313
                       = (CHOOS\ t\ x\ y\ T)\ (\iota\ [\lambda q.(\lor (\land T\ (=x\ q))\ (\land (\sim T)\ (=y\ q)))]) \qquad := \$LTMP5313
#
                       =_{ott}(CHOOS_{\langle 4o \rangle 3 \backslash 2\tau}t_{\tau}x_{t}y_{t}T_{o})\dots
\dots (\iota_{t(ot)}[\lambda q_t.(\vee_{ooo}(\wedge_{ooo}T_o(=_{ott}x_tq_t))(\wedge_{ooo}(\sim_{oo}T_o)(=_{ott}y_tq_t)))_o]) \qquad := \$LTMP5313
:= \$LTMP5313
\S s \% 0 15 \% 1
                       = (CHOOS t x y T) (\iota [\lambda q. (= x q)])
#
```

```
:= TMP5313 \%0
           2230 :
                           = (CHOOS t x y T) (\iota [\lambda q. (= x q)])_{\alpha}
                                                                     := TMP5313
# wff
## .4
## use Proof Template: A5205 Substitutions
:= $AA5205 o
# wff
           2 :
                                := $AA5205
                       O_{\tau}
:= \$BA5205 t_{\tau}
                               := \$BA5205
# wff
           4:
                       t_{\tau}
:= \ \$FA5205 \ =_{o \,\$BA5205 \,\$BA5205} x_{\$BA5205}
                                             := \$FA5205
           115 :
                         =x_{o\,\$BA5205}
<< a5205_substitutions.r0t.txt
:= $AA5205
:= \$BA5205
:= FA5205
\%0
                    = (= x) [\lambda y. (= x y)]
#
                    =_{o(ot)(ot)}(=_{ott}x_t)[\lambda y_t.(=_{ott}x_ty_t)_o]
#
\S r / 3 q_t
                    = [\lambda y.(=x y)] [\lambda q.(=x q)]
\S s \% 1 3 \% 0
                    = (= x) [\lambda q. (= x q)]
## use Proof Template A5201b (Swap): A = B \rightarrow B = A
<< A5201b.r0t.txt
\%0
                    = [\lambda q.(=xq)] (=x)
#
                    =_{o(ot)(ot)}[\lambda q_t.(=_{ott}x_tq_t)_o](=_{ott}x_t)
\%$TMP5313
                    = (CHOOS t x y T) (\iota [\lambda q. (= x q)])
                                                              := TMP5313
#
#
                     =_{ott}(CHOOS_{\langle 4o \rangle 3 \backslash 2\tau}t_{\tau}x_{t}y_{t}T_{o})(\iota_{t(ot)}[\lambda q_{t}.(=_{ott}x_{t}q_{t})_{o}])
                                                                                    := \$TMP5313
   TMP5313
\S s \% 0 7 \% 1
                    = (CHOOS t x y T) (\iota (= x))
#
:= TMP5313 \%0
                           = (CHOOS t x y T) (\iota (= x))_o := \$TMP5313
           2376 :
# wff
## .5
\%A5
                    = (\iota (= y)) y
                                    := A5
#
                    =_{ott}(\iota_{t(ot)}(=_{ott}y_t))y_t := A5
## use Proof Template A5221 (Sub): B \rightarrow B [x/A]
:= \$B5221 \%0
                          = (\iota (= y)) y_{\alpha}
# wff
           207 :
                                          := \$B5221 A5
```

```
:= T5221 t_{\tau}
                4:
                                                  T5221
# wff
                                t_{\tau}
:= \ \$X5221 \ y_{\$T5221}
# wff
                105 :
                                                              X5221
                                    y_{\$T5221}
:=  $A5221  x_{\$T5221}
# wff
                24 :
                                                      := $A5221
                                  x_{\$T5221}
<< A5221.r0t.txt
:= \$B5221
:= \$T5221
      X5221
:= $A5221
\%0
                             = (\iota (= x)) x
#
#
                             =_{ott}(\iota_{t(ot)}(=_{ott}x_t))x_t
\%$TMP5313
                             = (CHOOS t x y T) (\iota (= x))
#
                                                                                  := \$TMP5313
                                                                                                           := \$TMP5313
#
                             =_{ott}(CHOOS_{\langle 4o \rangle 3 \backslash 2\tau}t_{\tau}x_{t}y_{t}T_{o})(\iota_{t(ot)}(=_{ott}x_{t}))
     TMP5313
\$s \%0 3 \%1
                             = (CHOOStxyT)x
#
     LTMP5313 \%0
# wff
                2424 :
                                      = (CHOOS t x y T) x_0
                                                                                 := \$LTMP5313
## .6
\S = t_{\tau} CHOOS_{\langle 4o \rangle 3 \rangle 2\tau} t_{\tau} x_t y_t F_o
                             = (CHOOStxyF)(CHOOStxyF)
= (CHOOS\ t)\ [\lambda x.[\lambda y.[\lambda p.(\iota\ [\lambda q.(\lor (\land p\ (=x\ q))\ (\land (\sim p)\ (=y\ q)))])]]]
#
\$s \%1 24 \%0
                             = (CHOOS\ t\ x\ y\ F)\ ([\lambda x.[\lambda y.[\lambda p.(\iota\ [\lambda q.(\lor (\land p\ (=x\ q))\ (\land (\sim p)\ (=y\ q)))])]]]\ x\ y\ F)
#
 \{ \langle \lambda x_t [\lambda y_t [\lambda p_o.(\iota_{t(ot)}[\lambda q_t.(\vee_{ooo}(\wedge_{ooo}p_o(=_{ott}x_tq_t))(\wedge_{ooo}(\sim_{oo}p_o)(=_{ott}y_tq_t)))_o]\}_{t(tot)}] x_t \} 
                             = ([\lambda x.[\lambda y.[\lambda p.(\iota [\lambda q.(\vee (\wedge p (= x q)) (\wedge (\sim p) (= y q)))])]]]x) \dots
\dots [\lambda y.[\lambda p.(\iota [\lambda q.(\vee (\wedge p (= x q)) (\wedge (\sim p) (= y q)))])]]
\S s \% 1 12 \% 0
#
                             = (CHOOS\,t\,x\,y\,F)\,([\lambda y.[\lambda p.(\iota\,[\lambda q.(\vee\,(\wedge\,p\,(=\,x\,q))\,(\wedge\,(\sim\,p)\,(=\,y\,q)))])]]\,y\,F)
\{ \langle [\lambda y_t.[\lambda p_o.(\iota_{t(ot)}[\lambda q_t.(\vee_{ooo}(\wedge_{ooo}p_o(=_{ott}x_tq_t))(\wedge_{ooo}(\sim_{oo}p_o)(=_{ott}y_tq_t)))_o]\}_{t(to)} | y_t \rangle \}
                             = ([\lambda y.[\lambda p.(\iota [\lambda q.(\vee (\wedge p (= x q)) (\wedge (\sim p) (= y q)))])]] y) \dots
\dots [\lambda p.(\iota [\lambda q.(\vee (\wedge p (= x q)) (\wedge (\sim p) (= y q)))])]
\$s \%1 6 \%0
                             = (CHOOS\ t\ x\ y\ F)\ ([\lambda p.(\iota\ [\lambda q.(\lor (\land p\ (=x\ q))\ (\land (\sim p)\ (=y\ q)))])]\ F)
#
\{ \langle [\lambda p_o.(\iota_{t(ot)}[\lambda q_t.(\vee_{ooo}(\wedge_{ooo}p_o(=_{ott}x_tq_t))(\wedge_{ooo}(\sim_{oo}p_o)(=_{ott}y_tq_t)))_o] \}_t \} F_o
                             = ([\lambda p.(\iota [\lambda q.(\vee (\wedge p (= x q)) (\wedge (\sim p) (= y q)))])] F) \dots
\dots (\iota \left[\lambda q.(\vee (\wedge F (= x q)) (\wedge (\sim F) (= y q)))\right])
\$s \%1 3 \%0
                             = (CHOOS\,t\,x\,y\,F)\,(\iota\,[\lambda q.(\vee\,(\wedge\,F\,(=\,x\,q))\,(\wedge\,(\sim\,F)\,(=\,y\,q)))])
#
```

% A5231b

```
= (\sim F) T := A5231b
#
                     =_{ooo}(\sim_{oo}F_o)T_o := A5231b
#
\S s \% 1 125 \% 0
                     = (CHOOS t x y F) (\iota [\lambda q.(\lor (\land F (= x q)) (\land T (= y q)))])
:= \$TMP5313 \%0
                     : \qquad = (CHOOS\ t\ x\ y\ F)\ (\iota\ [\lambda q.(\vee(\wedge F\ (=x\ q))\ (\wedge T\ (=y\ q)))])_{o}
            2447
# wff
$TMP5313
\%K8001b
                     = (\wedge F x) F := K8001b
#
#
                     =_{ooo}(\wedge_{ooo}F_ox_o)F_o := K8001b
## use Proof Template A5221 (Sub): B \rightarrow B [x/A]
:= \$B5221 \%0
            1805 : = (\wedge F x) F_{o,...} := $B5221 K8001b
# wff
:= T5221 o
# wff
                        o_{\tau} := T5221
          2:
:= \$X5221 x_0
           16 :
                                 := $X5221
# wff
                       x_o
:= $A5221 \% 1/123
\# wff
                            = x q_{o, \dots} := \$A5221
           2064 :
<< A5221.r0t.txt
:= \$B5221
:= T5221
:= \$X5221
:= $A5221
\%0
                     = (\wedge F (= x q)) F
#
                     =_{ooo}(\wedge_{ooo}F_o(=_{ott}x_tq_t))F_o
\%$TMP5313
                     = (CHOOS\,t\,x\,y\,F)\,(\iota\,[\lambda q.(\vee\,(\wedge\,F\,(=\,x\,q))\,(\wedge\,T\,(=\,y\,q)))]) \qquad := \quad \$TMP5313
                     =_{ott}(CHOOS_{\backslash 4o\backslash 3\backslash 2\tau}t_{\tau}x_{t}y_{t}F_{o})\dots
\dots (\iota_{t(ot)}[\lambda q_t.(\vee_{ooo}(\wedge_{ooo}F_o(=_{ott}x_tq_t))(\wedge_{ooo}T_o(=_{ott}y_tq_t)))_o]) \qquad := \$TMP5313
:= \$TMP5313
\S s \% 0 61 \% 1
                     = (CHOOS t x y F) (\iota [\lambda q.(\forall F (\land T (= y q)))])
:= TMP5313 \%0
            2459 :
                           = (CHOOS\,t\,x\,y\,F)\,(\iota\,[\lambda q.(\forall\,F\,(\land\,T\,(=\,y\,q)))])_{\alpha} \qquad := \quad \$TMP5313
# wff
\%K8000b
                     = (\wedge T x) x := K8000b
#
                     =_{ooo}(\wedge_{ooo}T_ox_o)x_o := K8000b
## use Proof Template A5221 (Sub): B \rightarrow B [x/A]
:= \$B5221 \%0
                          = \left( \wedge \, T \, x \right) x_{o, \, \dots} \qquad := \quad \$B5221 \quad K8000b
            594 :
# wff
:= T5221 o
                        o_{\tau} := T5221
# wff
            2:
```

```
:= $X5221 x_o
# wff 16 :
                               := X5221
:= $A5221 \%1/63
# wff
         2069 :
                                        := \$A5221
                           = y q_o
<< A5221.r0t.txt
:= \$B5221
:= T5221
:= \$X5221
:= $A5221
\%0
                     = (\wedge T (= y q)) (= y q)
#
                     =_{ooo}(\wedge_{ooo}T_o(=_{ott}y_tq_t))(=_{ott}y_tq_t)
%TMP5313
                     = (CHOOS t x y F) (\iota [\lambda q.(\forall F (\land T (= y q)))]) \qquad := \$TMP5313
#
                          =_{ott}(CHOOS_{\backslash 4o\backslash 3\backslash 2\tau}t_{\tau}x_{t}y_{t}F_{o})(\iota_{t(ot)}[\lambda q_{t}.(\vee_{ooo}F_{o}(\wedge_{ooo}T_{o}(=_{ott}y_{t}q_{t})))_{o}])
$TMP5313
:= \$TMP5313
\S s \% 0 31 \% 1
                     = (CHOOS t x y F) (\iota [\lambda q.(\forall F (= y q))])
:= \$TMP5313 \%0
\# \text{ wff} \qquad 2471 :
                         = (CHOOS t x y F) (\iota [\lambda q.(\forall F (= y q))])_{o} := \$TMP5313
\%K8010b
                     = (\lor F x) x := K8010b
#
                     =_{ooo}(\vee_{ooo}F_ox_o)x_o := K8010b
#
## use Proof Template A5221 (Sub): B \rightarrow B [x/A]
:= \$B5221 \%0
                         = (\vee F x) x_0 := \$B5221 \ K8010b
# wff
           2058 :
:= T5221 o
                              := T5221
# wff
        2:
                       O_{\mathcal{T}}
:= $X5221 x_o
# wff
          16 :
                                 := \$X5221
                        x_o
:= $A5221 \%1/31
                           = y q_{o, \dots} := \$A5221
         2069 :
# wff
<< A5221.r0t.txt
:= \$B5221
:= T5221
:= \$X5221
:= $A5221
\%0
                     = (\vee F (= y q)) (= y q)
#
                     =_{ooo}(\vee_{ooo}F_o(=_{ott}y_tq_t))(=_{ott}y_tq_t)
\%$TMP5313
                     = (CHOOS t x y F) (\iota [\lambda q.(\forall F (= y q))]) := \$TMP5313
#
                     =_{ott}(CHOOS_{\langle 4o \rangle 3 \backslash 2\tau}t_{\tau}x_{t}y_{t}F_{o})(\iota_{t(ot)}[\lambda q_{t}.(\vee_{ooo}F_{o}(=_{ott}y_{t}q_{t}))_{o}]) \qquad := \$TMP5313
#
:= \$TMP5313
```

```
\S s \% 0 15 \% 1
                    = (CHOOS t x y F) (\iota [\lambda q. (= y q)])
:= \$TMP5313 \%0
                       = (CHOOS\,t\,x\,y\,F)\,(\iota\,[\lambda q.(=y\,q)])_o \qquad := \quad \$TMP5313
# wff
           2509 :
## .7
## use Proof Template: A5205 Substitutions
:= $AA5205 o
# wff
                               := \$AA5205
           2:
                       O_{\mathcal{T}}
:= \$BA5205 t_{\tau}
                      t_{	au}
                              := \$BA5205
# wff
          4:
:= \ \$FA5205 \ =_{o \,\$BA5205 \,\$BA5205} z_{\$BA5205}
# wff
           2510 : = z_{o \$BA5205}
                                           := \$FA5205
<< a5205_substitutions.r0t.txt
:= $AA5205
:= \$BA5205
:= FA5205
\%0
                    = (= z) [\lambda y. (= z y)]
#
                    =_{o(ot)(ot)}(=_{ott}z_t)[\lambda y_t.(=_{ott}z_ty_t)_o]
#
\S r / 3 q_t
                    = [\lambda y.(=z y)] [\lambda q.(=z q)]
\S s \% 1 3 \% 0
                    = (= z) [\lambda q. (= z q)]
## use Proof Template A5221 (Sub): B \rightarrow B [x/A]
:= \$B5221 \%0
# wff
                          = (=z) [\lambda q. (=zq)]_{\alpha}
           2529 :
                                                     := \$B5221
:= T5221 t_{\tau}
           4:
                              := T5221
# wff
                      t_{\tau}
:= \ \$X5221 \ z_{\$T5221}
\# wff
           83 :
                                     := \$X5221
                        z_{T5221}
:= $A5221 \ y_{\$T5221}
                                      := $A5221
# wff
           105 :
                         y_{T5221}
<< A5221.r0t.txt
:= \$B5221
:= T5221
:= \$X5221
:= $A5221
\%0
                    = (= y) [\lambda q. (= y q)]
#
                    =_{o(ot)(ot)}(=_{ott}y_t)[\lambda q_t.(=_{ott}y_tq_t)_o]
## use Proof Template A5201b (Swap): A = B \rightarrow B = A
<< A5201b.r0t.txt
\%0
                    = [\lambda q.(=yq)] (=y)
#
```

```
=_{o(ot)(ot)} [\lambda q_t \cdot (=_{ott} y_t q_t)_o] (=_{ott} y_t)
#
%TMP5313
                      = (CHOOS t x y F) (\iota [\lambda q. (= y q)])
                                                                  := \$TMP5313
#
#
                      =_{ott}(CHOOS_{\langle 4o \rangle 3 \backslash 2\tau}t_{\tau}x_{t}y_{t}F_{o})(\iota_{t(ot)}[\lambda q_{t}.(=_{ott}y_{t}q_{t})_{o}])
                                                                                         := TMP5313
:= \$TMP5313
\S s \% 0 7 \% 1
                      = (CHOOS t x y F) (\iota (= y))
#
\%A5
#
                      = (\iota (= y)) y
                                         := A5
#
                      =_{ott}(\iota_{t(ot)}(=_{ott}y_t))y_t := A5
\S s \% 1 3 \% 0
                      = (CHOOS t x y F) y
## .8
## use Proof Template K8020: A, B \rightarrow A \wedge B
:= \$A8020 =_{ott}(CHOOS_{\backslash 4o\backslash 3\backslash 2\tau}t_{\tau}x_{t}y_{t}T_{o})x_{t}
                             = (CHOOS t x y T) x_0
                                                                    A8020 LTMP5313
# wff
            2424 :
:= \$LTMP5313
:= $B8020 \%0
# wff
                             = (CHOOS t x y F) y_o
            2579 :
                                                              = \$B8020
<< K8020.r0t.txt
:= $A8020
:= \$B8020
:= A5313 \%0
            2614 : \wedge (= (CHOOStxyT)x) (= (CHOOStxyF)y)_{\alpha}
# wff
                                                                                                := A5313
##
      Q.E.D.
##
##
\%0
                      \wedge (= (CHOOS t x y T) x) (= (CHOOS t x y F) y) := A5313
#
                        \wedge_{ooo}(=_{ott}(CHOOS_{\backslash 4o\backslash 3\backslash 2\tau}t_{\tau}x_{t}y_{t}T_{o})x_{t})(=_{ott}(CHOOS_{\backslash 4o\backslash 3\backslash 2\tau}t_{\tau}x_{t}y_{t}F_{o})y_{t})
                                                                                                                       :=
A5313
            Results for File A6100.r0.txt
5.1.45
##
```

```
Proof A6100: Peano's Postulate No. 1 for Andrews' Definition of Natural Numbers
##
##
##
     Source: [Andrews 2002 (ISBN 1-4020-0763-9), p. 261]
##
##
     Copyright (c) 2015 Owl of Minerva Press GmbH. All rights reserved.
##
```

```
$E5209
:= T5209
:= $X5209
:= $A5209
\%0
#
                     = (= \$FA3 \$GA3) (\forall \$BA3 [\lambda x. (= (\$FA3 x) (\$GA3 x))])
                     =_{ooo} (=_{o(\$AA3\$BA3)(\$AA3\$BA3)} \$FA3_{\$AA3\$BA3} \$GA3_{\$AA3\$BA3}) \dots
... (\forall_{o(o\backslash 3)\tau}\$BA3_{\tau}[\lambda x_{\$BA3}.(=_{o\$AA3\$AA3}(\$FA3_{\$AA3\$BA3}x_{\$BA3})(\$GA3_{\$AA3\$BA3}x_{\$BA3}))_{o}])
## Include end (axiom3_substitutions.r0t.txt) [newfile=(axiom3_substitutions.r0.txt)]
>>>
##
##
       Undefine Syntactical Variables
##
    AA3
    \$BA3
:= \$FA3
   \$GA3
##
##
      Q.E.D.
##
\%0
                     = (= y z) (\forall u [\lambda x. (= (y x) (z x))])
#
                     =_{ooo}(=_{o(tu)(tu)}y_{tu}z_{tu})(\forall_{o(o\backslash 3)\tau}u_{\tau}[\lambda x_{u}.(=_{ott}(y_{tu}x_{u})(z_{tu}x_{u}))_{o}])
#
           Results for File axioms.r0.txt
5.1.86
##
##
       Axioms
##
##
##
       Source: [Andrews 2002 (ISBN 1-4020-0763-9), p. 213]
##
##
       Copyright (c) 2015 Owl of Minerva Press GmbH. All rights reserved.
##
       Written by Ken Kubota (<mail@kenkubota.de>).
##
##
       This file is part of the work "On the Theory of Mathematical Forms".
##
       For more information visit: <a href="http://dx.doi.org/10.4444/100.10">http://dx.doi.org/10.4444/100.10</a>
##
<< definitions1.r0.txt
```

##

```
##
      Axiom 1: Truth and Falsehood are the only truth values
##
:= A1 =_{ooo}(\land_{ooo}(g_{oo}T_o)(g_{oo}F_o))(\forall_{o(o\backslash 3)\tau}o_{\tau}[\lambda x_o.(g_{oo}x_o)_o])
# wff
           90 : = (\wedge (gT) (gF)) (\forall o [\lambda x.(gx)])_o
\S! A1
                    = (\wedge (gT) (gF)) (\forall o [\lambda x.(gx)]) := A1
#
##
##
      Axiom 2: One of the Basic Properties of Equality
##
:= A2 \supset_{ooo} (=_{oaa} x_a y_a) (=_{ooo} (h_{oa} x_a) (h_{oa} y_a))
           104 : \supset (=xy) (=(hx)(hy))_{0}
# wff
                                                          := A2
\S! A2
                    \supset (= x y) (= (h x) (h y)) := A2
#
##
##
      Axiom 3: Axiom of Extensionality
##
:= A3 =_{ooo}(=_{o(ab)(ab)} f_{ab} g_{ab}) (\forall_{o(o \setminus 3)\tau} b_{\tau} [\lambda x_b. (=_{oaa} (f_{ab} x_b) (g_{ab} x_b))_o])
           124 : = (= f g) (\forall b [\lambda x. (= (f x) (g x))])_0 := A3
# wff
§! A3
                    = (= f g) (\forall b [\lambda x. (= (f x) (g x))]) := A3
#
##
       Axiom 4: Axiom of Lambda Conversion
##
##
## Replaced by Rule 2 (Lambda Conversion)
## [cf. Andrews 2002 (ISBN 1-4020-0763-9), p. 218 f. (5207)]
##
## "5207 could be taken as an axiom schema in place of 4 1 - 4 5,
##
      and for some purposes this would be desirable,
      since 5207 has a conceptual simplicity and unity
##
##
       which is not apparent in 4 1 - 4 5." [Andrews 2002, p. 214]
##
      Axiom 5: Axiom of Descriptions
##
##
:= A5 =_{ott}(\iota_{t(ot)}(=_{ott}y_t))y_t
           129 : = (\iota(=y)) y_0 := A5
# wff
§! A5
```

```
\# \qquad = (\iota (=y)) y \qquad := A5
```

5.1.87 Results for File basics.r0.txt

```
##
##
      Basics
##
##
##
      Source: [Kubota 2015 (doi: 10.4444/100.10)]
##
      Copyright (c) 2015 Owl of Minerva Press GmbH. All rights reserved.
##
      Written by Ken Kubota (<mail@kenkubota.de>).
##
##
      This file is part of the work "On the Theory of Mathematical Forms".
##
      For more information visit: <a href="http://dx.doi.org/10.4444/100.10">http://dx.doi.org/10.4444/100.10</a>
##
##
<< definitions1.r0.txt
<< definitions2.r0.txt
<< definitions3.r0.txt
<< axioms.r0.txt
```

5.1.88 Results for File composition.r0.txt

```
##
##
         Associativity of the Composition of Functions
##
##
         Source: [Kubota 2015 (doi: 10.4444/100.10)]
##
##
##
         Copyright (c) 2015 Owl of Minerva Press GmbH. All rights reserved.
##
         Written by Ken Kubota (<mail@kenkubota.de>).
##
##
         This file is part of the work "On the Theory of Mathematical Forms".
         For more information visit: <a href="http://dx.doi.org/10.4444/100.10">http://dx.doi.org/10.4444/100.10</a>
##
##
<< basics.r0.txt
:= COMPS \dots
\dots [\lambda a_{\tau}.[\lambda b_{\tau}.[\lambda c_{\tau}.[\lambda g_{ab}.[\lambda f_{bc}.[\lambda x_{c}.(g_{ab}(f_{bc}x_{c}))_{a}]_{(ac)}]_{(ac(bc))}]_{(ac(bc)(ab))}]_{(a\backslash\{b\backslash\{a\},a\})}]_{(a\backslash\{b\backslash\{a\},a\})}]_{(a\backslash\{b\backslash\{a\},a\})}
                                   [\lambda a.[\lambda b.[\lambda c.[\lambda g.[\lambda f.[\lambda x.(g(fx))]]]]]]_{\land (\land (\backslash 5 \backslash 4)(\backslash 5 \backslash 4)\tau\tau\tau}
# wff
                233 :
## .1
:= \$GF \ COMPS_{\backslash 6\backslash 4(\backslash 5\backslash 4)(\backslash 5\backslash 4)\tau\tau\tau}u_{\tau}v_{\tau}w_{\tau}g_{uv}f_{vw}
                                   COMPSuvwgf_{uw}
# wff
                264 :
                                                                        := \$GF
```